Calculus I Recap

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IIT Bombay

Autumn Semester 2020-21

Start recording!

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Proposition 4 (Convergence \implies Cauchy)

If (a_n) is a convergent sequence in any space X, then (a_n) is Cauchy.

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Exercise: Show that \mathbb{N}, \mathbb{Z} are complete. (What property do you really need? Can you generalise this?)

Now, we digress a bit to see what $\ensuremath{\mathbb{R}}$ and completeness really means.

It is okay if you don't understand every single thing. It is more or less for you to know "okay, whatever we say works" even if you don't know the exact details why.

Week 1

What is \mathbb{R} ?

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$$egin{aligned} x < y \implies x + z < y + z ext{ for all } x, y, z \in \mathbb{R}, \ x < y \implies x \cdot z < y \cdot z ext{ for all } x, y \in \mathbb{R} ext{ and } z \in \mathbb{R}_{>0}. \end{aligned}$$

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Note that **neither** of the above grey boxes is true if we replace \mathbb{R} by \mathbb{Q} .

What one must really ask at this point is:

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For us, all we need to know is that convergence of a series is just the convergence of the <u>sequence</u> of its *partial sums*. Thus, we are back in the case where we study sequences!

We then moved on to the definition of limits of functions defined on intervals.

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If no such I exists, then we say that f does not have any limit at x_0 .

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Similarly, we have the limit at $-\infty$.

Stop recording. Start a new one. Take doubts.

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Start recording!

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We simply say "f is continuous" if it is continuous at every point in the domain. If f is not continuous at a point c in the domain, then we say that f is discontinuous at c. We have the usual rules which tell us that sum/product/composition of continuous functions is continuous.

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Note carefully that the domain is an interval.

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Aryaman Maithani Calculus I Recap

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Note very carefully that the above not only shows that the image of f is bounded but also that the bounds are attained! Note that the domain was a <u>closed and bounded</u> interval.
Recall that a (non-empty) set which is bounded above can have many upper bounds.

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Thus, what the previous theorem told us was that not only is the image bounded but the supremum and infimum are actually attained. (If the function is continuous and defined on a closed and bounded interval, that is.)

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In such a case, we call the value of the above limit the derivative of f at c and denote it by f'(c).
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Let $f: X \to \mathbb{R}$ be a function

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We then have the usual rules about product/sum/composition of differentiable functions again being differentiable. Of course, we **don't** have the naïve product rule but rather (fg)'(c) = f'(c)g(c) + f(c)g'(c). We then looked at minima/maxima.

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Of course, we have an analogous definition for minimum. Note that here, we have that x_0 is an "interior point." That is, there is an interval *around* x_0 contained within the domain.

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Once again, note that this only talks about "interior points."

We then saw Rolle's Theorem. Note the hypothesis carefully.

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Note that the derivative of a (differentiable) function need not be continuous. We shall see an example in the tutorial today, in fact. However, the above theorem tells us how the derivative can't have "jump" discontinuity.

Stop recording. Start a new one. Take doubts.

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Start recording!

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What did we see last week?

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What did we see last week? Continuity,

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What did we see last week? Continuity, IVP,

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What did we see last week? Continuity, IVP, EVT,

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What did we see last week? Continuity, IVP, EVT, sequential criterion,

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What did we see last week? Continuity, IVP, EVT, sequential criterion, derivative,

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2 $f''(x_0) < 0 \implies f$ has a local maximum at x_0 .

If $f''(x_0) = 0$, then nothing can be concluded.

We now look at concavity and convexity.

Definition 23 (Convex)

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The definition of a *concave* function is obtained by replacing \leq with \geq and "above" with "below."

Note that the definition does not even assume continuity.

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Note that the definition does not even assume continuity. In particular, the function need not be differentiable,

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Read it some day.

Proposition 24

Suppose $f: I \to \mathbb{R}$ is differentiable. Then

- f' is increasing on $I \iff f$ is convex on I.
- 2 f' is decreasing on $I \iff f$ is concave on I.
- f' is strictly increasing on $I \iff f$ is strictly convex on I.
- f' is strictly decreasing on $I \iff f$ is strictly concave on I.

Corollary 25

Suppose $f : I \to \mathbb{R}$ is twice differentiable. Then

- $f'' \ge 0$ on $I \iff f$ is convex on I.
- 2 $f'' \leq 0$ on $I \iff f$ is concave on I.
- $f'' > 0 \text{ on } I \implies f \text{ is strictly convex on } I.$
- f'' < 0 on $I \implies f$ is strictly concave on I.

Let's now talk about inflection points.

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Let x_0 be an *interior point* of *I*. Then, x_0 is called an inflection for *f* if there exists $\delta > 0$ such that either

- f is convex on $(x_0 \delta, x_0)$ and concave on $(x_0, x_0 + \delta)$, or
- 2 *f* is concave on $(x_0 \delta, x_0)$ and convex on $(x_0, x_0 + \delta)$.

As a crazy example, note that 0 is an inflection point of: $f: \mathbb{R} \to \mathbb{R}$ defined as

$$f(x) := \begin{cases} \frac{1}{x} & x \neq 0, \\ 0 & x = 0. \end{cases}$$

Note that f is not even continuous at 0.

Let's now talk about inflection points.

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Note that f is not even continuous at 0. Let alone twice differentiable. Also note that every point is a point of inflection for an affine function $x \mapsto ax + b$. (Even if a = 0.)

Here's some more information being thrown at you.

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Here's some more information being thrown at you. Look at it some day.

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Here's some more information being thrown at you. Look at it some day. Let $x_0 \in I$ be an *interior point*, and $f : I \to \mathbb{R}$.

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Theorem 27 (Derivative tests)

- (First derivative test) Suppose f is differentiable on
 (x₀ − r, x₀) ∪ (x₀, x₀ + r) for some r > 0. Then, x₀ is a point
 of inflection ⇔ there is δ > 0 with δ < r such that f' is
 increasing on (x₀ − δ, x₀) and f' is decreasing on (x₀, x₀ + δ),
 or vice-versa.
- ② (Second derivative test) Suppose *f* is twice differentiable on $(x_0 r, x_0) \cup (x_0, x_0 + r)$ for some r > 0. Then, x_0 is a point of inflection ⇔ there is $\delta > 0$ with $\delta < r$ such that $f'' \ge 0$ on $(x_0 \delta, x_0)$ and $f'' \le 0$ on $(x_0, x_0 + \delta)$, or vice-versa.

Thus, if f is twice differentiable, then x_0 is inflection point iff f'' changes sign. (Note that $f''(x_0)$ is not required to exist. Recall the crazy example.)

Theorem 28 (Another second derivative test)

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Theorem 29 (A **third** derivative test)

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Theorem 29 (A **third** derivative test)

Suppose f is thrice differentiable at x_0 such that $f''(x_0) = 0$ and $f'''(x_0) \neq 0$.
The previous slide gives us a **necessary** condition for inflection point. We have the same notation as earlier.

Theorem 28 (Another second derivative test)

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In the above, we are not assuming the existence of f'' at other points. The following is now a **sufficient** condition.

Theorem 29 (A **third** derivative test)

Suppose f is thrice differentiable at x_0 such that $f''(x_0) = 0$ and $f'''(x_0) \neq 0$. Then, x_0 is an inflection point for f.

Okay, that's enough about convex/concave/inflection points.

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Okay, that's enough about convex/concave/inflection points. Hopefully, any possible doubt about these is covered in the previous slides.

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Let's now look at Taylor polynomials.

Definition 30 (Taylor polynomials)

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Definition 30 (Taylor polynomials)

Let f be n times differentiable at x_0 . We define the n + 1 Taylor polynomials as

 $P_0(x) = f(x_0)$

Let's now look at Taylor polynomials. From now, I will be an open interval, a an interior point of I, and $f : I \to \mathbb{R}$ a function.

Definition 30 (Taylor polynomials)

$$P_0(x) = f(x_0)$$

$$P_1(x) = f(x_0) + \frac{f^{(1)}(x_0)}{1!}(x - x_0)$$

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$$\vdots$$

$$P_{n}(x) = f(x_{0}) + \frac{f^{(1)}(x_{0})}{1!}(x - x_{0}) + \dots + \frac{f^{(n)}(x_{0})}{n!}(x - x_{0})^{n}$$

Note that all the Taylor **polynomials** have only **finite**ly many terms, as a polynomial should have.

Theorem 31 (Taylor's theorem)

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Note that all the Taylor **polynomials** have only **finite**ly many terms, as a polynomial should have. Also note that so far, we have just defined some polynomials.

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Suppose that f is n + 1 times differentiable on I. Suppose that $b \in I$. Then, there exists $c \in (a, b) \cup (b, a)$ such that

$$f(b) = P_n(b) + \frac{f^{(n+1)}(c)}{(n+1)!}(b-a)^{n+1},$$

where P_n is as in the previous slide.

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Note that the Taylor series about some point *a* may still converge but *not* to *f*. Such a function is not called analytic.

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The last thing written
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Some final remarks:

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Suppose that the series converges on some interval J such that $a \in J \subset I$. It is not necessary that the Taylor series converges to f on J.

What was the example seen in class that illustrated this?

Stop recording. Start a new one. Take doubts.

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Definition 32 (Partitions)

Given a closed interval [a, b], a *partition* P of [a, b] is a <u>finite</u> collection of points

$$P = \{a = x_0 < x_1 < \cdots < x_n = b\}.$$

Note that a partition P is really just a subset of [a, b] with the requirement that it must be finite and contain a and b. It is customary to then list it in increasing order.

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Given two partitions P_1 and P_2 of [a, b], we see that $P = P_1 \cup P_2$ is also a partition of [a, b].

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Given two partitions P_1 and P_2 of [a, b], we see that $P = P_1 \cup P_2$ is also a partition of [a, b]. Moreover, P is a refinement of both P_1 and P_2 . In other words, any two partitions have a <u>common refinement</u>.

Definition 34

Aryaman Maithani Calculus I Reca

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Definition 34

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$$M_i := \sup_{x \in [x_{i-1}, x_i]} f(x)$$
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Thus, m_i and M_i denote the infimum and supremum of f over the *i*-th interval, respectively.

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Given everything as in the previous slide, we define lower/upper sums as following.

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In the above, note that we have both f and P in the notation. This is crucial because the sums depend on the partition.

Using the earlier sums, we now define the upper and lower Darboux *integrals*. The notations are continuing from earlier.

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Note that the sup / inf is over all the partitions P of [a, b].

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Note that the sup / inf is over all the partitions P of [a, b].

Note that the notation now does not have any P. This is because L(f) and U(f) don't depend on any specific partition.

Definition 37 (Darboux integrable)

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A <u>bounded</u> function $f : [a, b] \rightarrow \mathbb{R}$

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A <u>bounded</u> function $f : [a, b] \to \mathbb{R}$ is said to be *Darboux integrable* if L(f) = U(f). In this case, we define

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We now turn to the definition of Riemann integrals.

Some jargon.

Definition 40 (Norm of a partition)

Definition 41 (Tagged partition)

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In other words, it is the length of the largest sub-interval.

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Given a partition P of [a, b] as before, we get the intervals $I_i = [x_{i-1}, x_i]$ for i = 1, ..., n. For each i, we pick a point $t_i \in I_i$. This collection of points together is denoted by t. The pair (P, t) is called a *tagged partition* of [a, b].

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Let $f : [a, b] \to \mathbb{R}$ be a function. Let (P, t) be a tagged partition of [a, b]. We define the *Riemann sum* associated to f and (P, t) by

$$R(f, P, t) := \sum_{i=1}^{n} f(t_i)(x_i - x_{i-1}).$$

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Note that the notation here includes f, P, and t.

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Note that the notation here includes f, P, and t. Also note that here we didn't demand f be bounded.

On the next slide, we state two equivalent definitions of Riemann integrability.

Definition 43 (Riemann 1)

Definition 44 (Riemann 2)

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Definition 43 (Riemann 1)

A function $f : [a, b] \rightarrow \mathbb{R}$

Definition 44 (Riemann 2)

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A function $f : [a, b] \rightarrow \mathbb{R}$ is said to be *Riemann integrable*

Definition 44 (Riemann 2)

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A function $f : [a, b] \to \mathbb{R}$ is said to be *Riemann integrable* if for there exists $R \in \mathbb{R}$

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A function $f : [a, b] \to \mathbb{R}$ is said to be *Riemann integrable* if for there exists $R \in \mathbb{R}$ such that for every $\epsilon > 0$, there exists $\delta > 0$ such that

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for all tagged partitions (P, t)

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A function $f : [a, b] \to \mathbb{R}$ is said to be *Riemann integrable* if for there exists $R \in \mathbb{R}$ such that for every $\epsilon > 0$, there exists $\delta > 0$ and a partition P such that

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A function $f : [a, b] \to \mathbb{R}$ is said to be *Riemann integrable* if for there exists $R \in \mathbb{R}$ such that for every $\epsilon > 0$, there exists $\delta > 0$ and a partition P such that

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for all tagged refinements (P', t') of P with $||P'|| < \delta$.

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Theorem 46 (Darboux and Riemann are friends)

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In both the definitions on the earlier slide, the R is unique and it is called the *Riemann integral* of f over [a, b].

Theorem 46 (Darboux and Riemann are friends)

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Theorem 46 (Darboux and Riemann are friends)

Let $f : [a, b] \to \mathbb{R}$ be a function.

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In both the definitions on the earlier slide, the R is unique and it is called the *Riemann integral* of f over [a, b].

Theorem 46 (Darboux and Riemann are friends)

Let $f : [a, b] \to \mathbb{R}$ be a function. If f is bounded and Darboux integrable, then f is also Riemann integrable.

In both the definitions on the earlier slide, the R is unique and it is called the *Riemann integral* of f over [a, b].

Theorem 46 (Darboux and Riemann are friends)

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In both the cases above, the Darboux and Riemann integrals are the same.

Aryaman Maithani Calculus I Recap

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Theorem 47 (Riemann sums approximating the integral)

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The converse of the previous theorem is not true. In fact, the theorem is true even if we assume something less. Namely, if f is bounded and is discontinuous on a finite set, then it is Riemann integrable.

The "at most countable" can actually be replaced with "measure zero."

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Now, we see how derivatives and integrals relate. These are the two parts of the Fundamental Theorem of Calculus.

Aryaman Maithani Calculus I Recap

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In particular, if f is continuous,
Theorem 49 (FTC Part I)

Let $f : [a, b] \rightarrow \mathbb{R}$ be a Riemann integrable function, and let

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Theorem 49 (FTC Part I)

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F'(c)=f(c).

In particular, if f is continuous, then Riemann integrability of f is guaranteed and the above equation is true for all $c \in (a, b)$.

Aryaman Maithani Calculus I Recap

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Note that the if is crucial. It isn't necessary that the derivative of a function is Riemann integrable. It needn't even be bounded. (But even if it is bounded, it needn't be Riemann integrable. Although an example of this is harder.)

Some pathological remarks:

- If a function is Riemann integrable, it doesn't mean that it is the derivative of a function. (That is, it needn't have an anti-derivative.)
- If a function has an anti-derivative, it doesn't mean that it is Riemann integrable. (That is, derivatives needn't be Riemann integrable.)

For the first, take $f : [0, 2] \to \mathbb{R}$ defined by $f(x) = \lfloor x \rfloor$. It cannot be the derivative of any function because it doesn't have IVP. (Recall Theorem 21.)

For the second, consider the derivative of $F : [-1,1] \to \mathbb{R}$ defined by $F(x) = x^2 \sin(1/x^2)$ for $x \neq 0$ and F(0) = 0. F' here isn't bounded. Start recording!

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Definition 51 (Limits)

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In whatever follows, $n, m \ge 1$ and U will be a subset of \mathbb{R}^n .

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Let $f : U \to \mathbb{R}^m$ be a function and $c \in \mathbb{R}^n$ be a limit point of U. Let $L \in \mathbb{R}^m$.

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Let $f : U \to \mathbb{R}^m$ be a function and $c \in \mathbb{R}^n$ be a limit point of U. Let $L \in \mathbb{R}^m$. We write

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if for every $\epsilon > 0$, there exists $\delta > 0$ such that

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for all $x \in U$ such that $0 < ||x - c|| < \delta$.

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Note that if m = 1, then ||f(x) - L|| is just |f(x) - L|.

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Note that if m = 1, then ||f(x) - L|| is just |f(x) - L|. In fact, for n = m = 1, the definition above coincides with the earlier one. (Definition 10.)

In the previous slide, we used the phrase "limit point."

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Definition 52 (Limit point)Let $U \subset \mathbb{R}^n$

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Note that a limit point of U can lie outside U.

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To see this, consider n = 1 and $U = [0, 1) \cup \{2\}$.

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Note that a limit point of U can lie outside U. Conversely, a point in U could still fail to be a limit point of U.

To see this, consider n = 1 and $U = [0, 1) \cup \{2\}$. Then, 1 is a limit point of U while 2 is not.

Definition 53 (Continuity)

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If $f: U \to \mathbb{R}^m$ is a function and $c \in U$, then f is said to be *continuous at the point* c if (and only if)

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As before, the case n = m = 1 recovers the original one.

Now, let us assume n = 2 and m = 1.

Definition 54 (Partial derivative)

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Now, let us assume n = 2 and m = 1. That is, $U \subset \mathbb{R}^2$ and we look at functions of the form $f : U \to \mathbb{R}$.

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$$\frac{\partial f}{\partial x_1}(a,b) := \lim_{x_1 \to a} \frac{f(x_1,b) - f(a,b)}{x_1 - a},$$

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provided that the limit exists.

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The partial derivative with respect to x_2 is defined similarly.

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The partial derivative with respect to x_2 is defined similarly. Note that the limit above is an ordinary one-variable limit of a real function, as we had seen earlier.

Now, let us assume n = 2 and m = 1. That is, $U \subset \mathbb{R}^2$ and we look at functions of the form $f : U \to \mathbb{R}$.

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provided that the limit exists.

The partial derivative with respect to x_2 is defined similarly. Note that the limit above is an ordinary one-variable limit of a real function, as we had seen earlier. Also note that b is fixed in the numerator. In the previous slide, we used the phrase "interior point."

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Definition 55 (Interior point) Let $U \subset \mathbb{R}^n$ and $c \in U$.

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Definition 55 (Interior point)

Let $U \subset \mathbb{R}^n$ and $c \in U$. c is said to be an *interior point* of U if there exists $\delta > 0$ such that for every $x \in \mathbb{R}^n$ with $||x - c|| < \delta$, we have $x \in U$.

The above says that not only is $c \in U$ but also that there is a "ball" around c contained in U.

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The above says that not only is $c \in U$ but also that there is a "ball" around c contained in U.

Note that the above says "there exists" and not "for every."

Definition 55 (Interior point)

Let $U \subset \mathbb{R}^n$ and $c \in U$. *c* is said to be an *interior point* of *U* if there exists $\delta > 0$ such that for every $x \in \mathbb{R}^n$ with $||x - c|| < \delta$, we have $x \in U$.

The above says that not only is $c \in U$ but also that there is a "ball" around c contained in U.

Note that the above says "there exists" and not "for every." Compare this with the definition of "limit point."

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Let $f: U \to \mathbb{R}$ be a function

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Image: A matrix and a matrix

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$$\nabla_{v}f(x) = \lim_{t\to 0}\frac{f(x_1+tv_1,x_2+tv_2)-f(x_1,x_2)}{t},$$

provided it exists.

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As before, this is an ordinary limit.

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provided it exists.

As before, this is an ordinary limit. Taking v = (1,0) and (0,1) recovers the usual the partial derivatives with respect to x_1 and x_2 , respectively.

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In this case, we write $Df(x_0, y_0) = A$ and call A the total derivative of f at (x_0, y_0) .

In your slides, we had seen originally seen a different definition.

Theorem 58

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Theorem 58

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Theorem 58

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The above matrix is also called the *gradient* and denoted by $\nabla f(x_0, y_0)$.

Stop recording. Start a new one. Take doubts.

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Start recording!

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Note that in my slides, I had actually defined the limit and continuity of vector valued functions of the form $f : \mathbb{R}^m \to \mathbb{R}^n$ last week itself.

Observe that given a function $f: U \to \mathbb{R}^n$,

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If n = m, these vector valued functions are called vector fields.

We now look at the derivative of a vector valued function. As earlier, $U \subset \mathbb{R}^m$.

Definition 59 (Differentiability)

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Note in the above that h is a column matrix in the red space - \mathbb{R}^m , that is, the domain space. In the limit, note that the value in the numerator (inside the mod) is in \mathbb{R}^n and denominator in \mathbb{R}^m .

Just like in the case of $\mathbb{R}^2 \to \mathbb{R}$, the general appearance of the derivative, if it exists, is quite simple:

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$$Df(x) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1}(x) & \cdots & \frac{\partial f_1}{\partial x_m}(x) \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial x_1}(x) & \cdots & \frac{\partial f_n}{\partial x_m}(x) \end{bmatrix}$$

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Note that partial derivatives (as seen so far) only make sense for <u>real valued</u> functions.

Aryaman Maithani Calculus I Recap

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Suppose we have functions as following:

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Theorem 60 (Chain rule)

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Assume that f is differentiable at $x \in \mathbb{R}^m$

Theorem 60 (Chain rule)

Suppose we have functions as following:

$$\mathbb{R}^m \xrightarrow{f} \mathbb{R}^n \xrightarrow{g} \mathbb{R}^p.$$

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Assume that f is differentiable at $x \in \mathbb{R}^m$ and g at f(x). Then $g \circ f : \mathbb{R}^m \to \mathbb{R}^p$ is differentiable at x and the $p \times m$ derivative matrix $D(g \circ f)(x)$ is given by

$$D(g \circ f)(x) = [Dg(f(x))] \circ Df(x),$$

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where \circ on the right is matrix multiplication.

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Note that the matrix multiplication makes sense because Dg(f(x)) is a $p \times n$ matrix and Df(x) an $n \times m$ matrix. Moreover, the product is a $p \times m$ matrix, as expected.

Aryaman Maithani Calculus I Reca

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Let $f: U \to \mathbb{R}$ be a <u>real valued</u> function

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Let $f: U \to \mathbb{R}$ be a <u>real valued</u> function such that the partial derivatives $\frac{\partial}{\partial x_i} \left(\frac{\partial}{\partial x_j} f \right)$ exist and are continuous

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for all $1 \leq i, j \leq m$.

In other words, the order of the *mixed partial* is irrelevant.

Let $f: U \to \mathbb{R}$ be a <u>real valued</u> function such that the partial derivatives $\frac{\partial}{\partial x_i} \left(\frac{\partial}{\partial x_j} f \right)$ exist and are continuous for all $1 \le i, j \le m$. Then $\frac{\partial}{\partial x_i} \left(\frac{\partial}{\partial x_i} f \right) = \frac{\partial}{\partial x_i} \left(\frac{\partial}{\partial x_i} f \right)$

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A function satisfying the hypothesis of the above theorem is said to be a \mathcal{C}^2 function.

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A function satisfying the hypothesis of the above theorem is said to be a \mathcal{C}^2 function.

A counterexample for the partials not being equal is given on the next slide.

Let $f: U \to \mathbb{R}$ be a <u>real valued</u> function such that the partial derivatives $\frac{\partial}{\partial x_i} \left(\frac{\partial}{\partial x_j} f \right)$ exist and are continuous for all $1 \le i, j \le m$. Then $\frac{\partial}{\partial x_i} \left(\frac{\partial}{\partial x_i} f \right) = \frac{\partial}{\partial x_i} \left(\frac{\partial}{\partial x_i} f \right)$

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A function satisfying the hypothesis of the above theorem is said to be a \mathcal{C}^2 function.

A counterexample for the partials not being equal is given on the next slide. Of course, the function is not \mathcal{C}^2 in that case.

The promised counterexample:

Example 62 (Inequality of mixed partials)

Let $f : \mathbb{R}^2 \to \mathbb{R}$ be defined by

$$f(x,y) := \begin{cases} \frac{xy(x^2 - y^2)}{x^2 + y^2} & (x,y) \neq (0,0), \\ 0 & (x,y) = (0,0). \end{cases}$$

Then,

$$\frac{\partial}{\partial x_2} \left(\frac{\partial}{\partial x_1} f \right) (0,0) = -1 \neq 1 = \frac{\partial}{\partial x_1} \left(\frac{\partial}{\partial x_2} f \right) (0,0).$$

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Definition 64 (Local minimum)

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Let $U \subset \mathbb{R}^2$

Definition 64 (Local minimum)

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Let $U \subset \mathbb{R}^2$ and $(x_0, y_0) \in U$ be an interior point.

Definition 64 (Local minimum)

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Let $U \subset \mathbb{R}^2$ and $(x_0, y_0) \in U$ be an interior point. (x_0, y_0) is called a *critical point* of f

Definition 64 (Local minimum)

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Let $U \subset \mathbb{R}^2$ and $(x_0, y_0) \in U$ be an interior point. (x_0, y_0) is called a *critical point* of f if $\nabla f(x_0, y_0) = [0 \ 0]$.

Definition 64 (Local minimum)

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$$D_r(x_0, y_0) = \{(x, y) \mid ||(x, y) - (x_0, y_0)|| < r\}$$

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Let $U \subset \mathbb{R}^2$ and $(x_0, y_0) \in U$ be an interior point. Then, we say that f attains a *local minimum* at (x_0, y_0) if there exists r > 0 such that the disc

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The above can be seen as a certain determinant.

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- If D = 0, the test says nothing.

Note that the above only gives information on the *interior* of U. To get a global minimum on a (bounded) *closed* rectangle, we would also have to look at the *boundary*.

Some concluding facts about multi-variable functions.

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 If f is differentiable at a point, then f is continuous at that point and all directional derivatives at that point exist. Moreover,

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- **2** If f_x and f_y exist at a point, it does not imply that the other directional derivatives do too.
- If all directional derivatives exist at a point, it does not imply that f is continuous at that point. In particular, f need not be differentiable at that point.

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- Note that, by definition, if a critical point is not a local extremum, then it must be a saddle point.
Some things regarding the second derivative test.

- If you get D = 0 in the last test, you would have to analyse the function on your own and try to find out the behaviour. (We shall do this in a tutorial question today.)
- Note that, by definition, if a critical point is not a local extremum, then it must be a saddle point. In other words, a critical point is either a point of local extremum or a saddle point.

And for the last time.

Stop recording. Start a new one. Take doubts.

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