

ODEs TSC

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IIT Bombay

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The ODE is said to be **linear** if it of the form

$$a_n(x)y^{(n)}(x) + \cdots + a_0(x)y = b(x)$$

for some $n \geq 0$ and functions a_0, \dots, a_n, b of x .

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Example: $x^2 + y^2 = 25$.

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Solving it gives $y = cx$ ($c \in \mathbb{R}$) as the family of orthogonal trajectories.

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$$H_1(x) + H_2(y) = c$$

for $c \in \mathbb{R}$.

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To solve: put $y = xv$ and things “magically” fall in place by becoming a separable ODE in v .

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Just integrate the above to get $k(y)$ and in turn, get $u(x, y)$.

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$$\mu = \exp\left(\int \frac{M_y - N_x}{N} dx\right).$$

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Definition and existence

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An non-example of Lipschitz function (in y) is: $f(x, y) = \sqrt{|y|}$ defined on $[-1, 1] \times [-1, 1]$. Similarly, $f(x, y) = y^2$ is not Lipschitz w.r.t. y on \mathbb{R}^2 but is so on bounded domains.

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As before, there may a solution on a larger interval. Moreover, there may still be a larger interval where the solution is unique.

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Under the assumptions of the existence-uniqueness theorem, the above converges to the solution y of the IVP defined by $y(x) := \lim_{n \rightarrow \infty} y_n(x)$.

Table of Contents

- 1 Basics
- 2 Specific (JEE) ODEs
- 3 Exact ODEs
- 4 IVP
- 5 Linear ODEs**
- 6 Specific second order linear ODEs
- 7 n -th order linear ODE
- 8 Laplace transform

Definition and convention

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Disclaimer

Our results will always assume that the ODE is in standard form. This is crucial.

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The standard ODE is said to be **homogeneous** if $b(x) = 0$, i.e., it is of the form

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(Bernoulli) If the ODE was instead $y' + P(x)y = Q(x)y^n$ for some $n \neq 0, 1$, then substitute $v = y^{1-n}$ and it will “magically” get reduced to the above.

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Theorem 7 (Dimension result)

The solution space of (2) is a two-dimensional real vector space.

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Again, note that no reference to any DE has been made.

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Note that basis being $\{y_1, y_2\}$ means that the general solution is given by $c_1y_1 + c_2y_2$ for $c_1, c_2 \in \mathbb{R}$.

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(Dimension result) The solution space of (3) is n -dimensional.

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Consider the non-homogeneous ODE

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The coefficients a_0, \dots, a_k are obtained by plugging y_p in (4) and comparing coefficients.

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The method of undetermined coefficients for Cauchy-Euler is the same with obvious modifications.

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For $c \geq 0$, define the Heaviside function u_c by

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Linearity: $\mathcal{L}(af + bg) = a\mathcal{L}(f) + b\mathcal{L}(g)$ for functions f, g and reals a, b .

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Laplace of common functions

$f(t)$	$F(s)$	$f(t)$	$F(s)$
t	$1/s^2$	t^a	$\frac{\Gamma(a+1)}{s^{a+1}}$
$u_c(t)$	e^{-cs}/s	e^{at}	$\frac{1}{s-a}$
$\sin(\omega t)$	$\frac{\omega}{s^2 + \omega^2}$	$\cos(\omega t)$	$\frac{s}{s^2 + \omega^2}$
$t \sin(\omega t)$	$\frac{2\omega s}{(s^2 + \omega^2)^2}$	$t \cos(\omega t)$	$\frac{s^2 - \omega^2}{(s^2 + \omega^2)^2}$
$e^{at} \sin(\omega t)$	$\frac{\omega}{(s-a)^2 + \omega^2}$	$e^{at} \cos(\omega t)$	$\frac{s-a}{(s-a)^2 + \omega^2}$
$\sinh(\omega t)$	$\frac{\omega}{s^2 - \omega^2}$	$\cosh(\omega t)$	$\frac{s}{s^2 - \omega^2}$
$e^{at} \sinh(\omega t)$	$\frac{\omega}{(s-a)^2 - \omega^2}$	$e^{at} \cosh(\omega t)$	$\frac{s-a}{(s-a)^2 - \omega^2}$

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We have another theorems which says that if $F = \mathcal{L}(f)$, then $\lim_{s \rightarrow \infty} F(s) = 0$. For example, this rules out 1 , $\sin(s)$, $\log(s^2 + 1)$, $\log(s^{-1})$ from being Laplace transforms.

Examples of some Laplace inverses

For $a \in \mathbb{R}$ and $n \geq 1$, we have

$$\mathcal{L}^{-1} \left(\frac{1}{(s-a)^n} \right) = \frac{1}{n!} e^{at} t^{n-1}.$$

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Sometimes, it may be useful to use derivatives. For example, if we wish to compute the Laplace inverse of $F(s) = \log \left(\frac{s^2 + 1}{s^2 + 4} \right)$, we note that

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$F'(s) = \frac{2s}{s^2+1} - \frac{2s}{s^2+4}$. Now, we can take Laplace inverse and using $\mathcal{L}(tf(t)) = -F'(s)$, we get the desired f .